# COLLISION OF JETS EMERGING FROM CHANNELS <br> WITH PARALLEL WALLS 

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Much effort in the past several years has gone into the investigation, development, and design of digital computers and devices capable of carrying out logical operations and performing control functions by means of fluid-jet elements. These devices are intended to carry out the same operations as electronic circuits. Jet elements are also used in various types of sensing and operating equipment [ ${ }^{1,2}$,
Jet elements are based on two principal mechanisms: a) the interaction of liquid or gas jets, and b) stream-wall interaction (the so-called Coanda effect). Jet elements usually combine both of these mechanisms [] $]$.

Cronin [ ${ }^{3}$ ] used conformal mapping to solve the problem of collision of jets emerging from channels with parallel walls for the case of an incompressible fluid with special reference to jet amplifiers. However, he did not obtain analytical expressions in finite form for the required quantities; his computations for an angle of $18^{\circ}$ between the channel axes are carried out by numerical integration.

In the present paper we consider the collision of gas jets emerging from channels with parallel walls whose axes form an arbitrary angle. The flow is assumed to be subsonic, planar, steady, potential, and adiabatic. The problem is solved by the method of Chaplygin [ ${ }^{4}$ ] as generalized by Fal'kovich [ ${ }^{6}$ ] for the case of several characteristic velocities. This enables us to find expressions for the stream function, the jet compression coefficient, and the geometric flow elements. We extend the solution to the case of an incompressible fluid by a limiting process. Analytical formulas in closed form are obtained for the case where the channel axes are at right angles to each other. These formulas were used as a basis for detailed numerical calculations.

Our results can be used for computing the geometric characteristics of discrete-action jet amplifiers and analog-type jet amplifiers $\left[{ }^{2}\right]$.

1. Let us consider the collision of jet streams emerging from channels of finite width and parallel walls. Two of the walls meet at the point $O$ and form the angle $\alpha=\sigma \pi \quad(0<\sigma \leqslant 1)$ (Fig. 1).


Fig. 1


Fig. 2

Here $O C, A B, O E, F D$ are the channel walls; $A M, F D$ are the free jet surfaces; $v_{1}, v_{2}, v_{3}$ are the gas velocities at the infinitely distant channel cruss sections
$B C, E D$ and at the jet cross section $M N ; \rho_{1}, \rho_{2}, \rho_{3}$ are the gas densities at the same cross sections; $h_{1}, h_{2}, \delta$ are the widths of the channels and of the confluent jet at infinity; $m$ is the angle of inclination of the jet to the $x$-axis at infinity.

We assume that the flow is planar, subsonic, steady, potential, and adiabatic, and that the gas in both channels is of the same nature. We shall limit ourselves to the case where the jet boundary $O L$ is not a line of discontinuity, but rather a streamline common to the two flows along which the gas parameters vary continuously. The potential solutions for both jets are therefore analytical continuations of each other. This implies, in turn, that an analytical solution for the two flows together can be obtained by the usual method applied to potential flow problems. The criterion of continuity of the flow parameters along the boundary $O L$ in a certain special case is given in [ ${ }^{6}$ ].

Let us assume that along the streamlines $C O L$ and $E O L$ meeting at the point $O$ the stream function $\psi=0$. If we denote the gas discharge rates at the cross sections $B C$, and $E D$ by $Q_{1}$ and $Q_{2}$, respectively, and the gas discharge rate at the cross section $M N$ by $Q$, so that

$$
\begin{equation*}
Q=Q_{1}+Q_{\mathbf{2}} \tag{1.1}
\end{equation*}
$$

then the stream function is $\psi=Q_{1}$ on the streamline $B A M$ and $\psi=-Q_{2}$ on the streamline $D F M$.

In the plane of the velocity hodograph with the polar coordinates $\tau, \theta$, i.e. in the plane of the variables $\tau=v^{2} / v_{\max }{ }^{2}$ (where $v$ is the velocity, $v_{\max }$ the maximum velocity, and $\theta$ the angle of inclination of the velocity to the $x$-axis (Fig. 1)) the flow domain under consideration can be represented as a circular sector of radius $\tau_{8}$ and the vertex angle $\alpha$ (Fig. 2). The boundary conditions are

$$
\begin{array}{ll}
\psi=0 & \text { for } \theta=0,0 \leqslant \tau \leqslant \tau_{1} \\
\psi=Q_{1} & \text { for } \theta=0, \tau_{1} \leqslant \tau \leqslant \tau_{3} \\
\psi=0 & \text { for } \theta=\sigma \pi, 0 \leqslant \tau \leqslant \tau_{2} \\
\psi=-Q_{2} & \text { for } \theta=\sigma \pi, \tau_{2} \leqslant \tau \leqslant \tau_{3} \\
\psi=Q_{1} & \text { for } \tau=\tau_{3}, 0 \leqslant \theta \leqslant m \\
\psi=-Q_{2} & \text { for } \quad \tau=\tau_{3} m \leqslant \theta \leqslant \sigma \pi \tag{1,3}
\end{array}
$$

We have thus reduced solution of our problem to finding the solution of the interior Dirichlet problem for Chaplygin's equation

$$
\begin{equation*}
4 \tau^{2}(1-\tau) \frac{\partial^{2} \psi}{\partial \tau^{2}}+4 \tau[1+(\beta-1) \tau] \frac{\partial \psi}{\partial \tau}+[1-(2 \beta+1) \tau] \frac{\partial{ }^{2} \psi}{\partial \theta^{2}}=0 \tag{1.4}
\end{equation*}
$$

in the appropriate subregions of the circular sector. Here $\beta=1 /(x-1)$, $\mathcal{H}=C_{p} / C_{v}$. Since $\tau<1 /(2 \beta+1)$, it follows that Eq. (1.4) is an elliptic equation in the region under consideration.

Following [b], we shall seek the solution of the problem in the form

$$
\begin{gather*}
\psi_{1}(\tau, \theta)=\sum_{n=1}^{\infty} a_{n} z_{\lambda}(\tau) \sin \lambda \theta, \quad \lambda=\frac{n}{s} \\
\psi_{2}(\tau, \theta)=Q_{1} \frac{\sigma \pi-\theta}{\sigma \pi}+\sum_{n=1}^{\infty}\left[A_{n} z_{\lambda}(\tau)+\beta_{n} \sigma_{\lambda}(\tau)\right] \sin \lambda \theta  \tag{1.5}\\
\psi_{3}(\tau, \theta)=Q_{1}-Q \frac{\theta}{\sigma \pi}+\sum_{n=1}^{\infty}\left[C_{n} z_{\lambda}(\tau)+D_{n} \zeta_{\lambda}(\tau)\right] \sin \lambda \theta
\end{gather*}
$$

Here the subscript of $\psi$ denotes the number of the subregion of the circular sector to which the solution refers: $z_{\lambda}(\tau)$ is the integral of the equation

$$
\begin{equation*}
4 \tau^{2}(1-\tau) Z_{\lambda}{ }^{n}+4 \tau[1+(\beta-1) \tau] Z_{\lambda}^{\prime}-\lambda^{2}[1-(2 \beta+1) \tau] Z_{\lambda}=0 \tag{1.6}
\end{equation*}
$$

which is regular for $\tau=0 ; \zeta_{\lambda}(\tau)$ is the second linearly independent integral of Eq. (1.6) obtained by Lighthill $[7]$ and Cherry $[8,9]$ and first used in the theory of gas jets by Fal kovich [5]. For the Wronskian of these integrals we have

$$
\begin{equation*}
w_{\lambda}(\tau)=z_{\lambda}{ }^{\prime}(\tau) \zeta_{\lambda}(\tau)-\zeta_{\lambda}{ }^{\prime}(\tau) z_{\lambda}(\tau)=\lambda(1-\tau)^{3} \tau^{-1} \tag{1.7}
\end{equation*}
$$

The coefficients $a_{n} . A_{n}, \ldots, D_{n}$ must be determined.
The stream functions given by (1.5) satisfy boundary conditions (1.2). Now let us require fulfillment of boundary conditions (1.3) and of the conditions of analytical continuation through the subregion boundaries,i.e.

$$
\begin{array}{lll}
\psi_{1}\left(\tau_{1}, \theta\right)=\psi_{3}\left(\tau_{1}, \theta\right), & \frac{\partial \psi_{1}}{\partial \tau}=\frac{\partial \psi_{2}}{\partial \tau} \quad \text { for } \quad \tau=\tau_{1}, 0 \leqslant \theta \leqslant \sigma \pi \\
\psi_{3}\left(\tau_{3}, \theta\right)=\psi_{3}\left(\tau_{1}, \theta\right), & \frac{\partial \psi_{2}}{\partial \tau}=\frac{\partial \psi_{2}}{\partial \tau} \quad \text { for } \quad \tau=\tau_{2}, 0 \leqslant 0 \leqslant \sigma \pi \tag{1.8}
\end{array}
$$

Conditions (1.3) and (1.8) yield the system of equations

$$
\begin{gathered}
C_{n} z_{\lambda}\left(\tau_{3}\right)+D_{n} \zeta_{\lambda}\left(\tau_{3}\right)=-(2 Q / n \pi) \cos \lambda m \\
\left(A_{n}-a_{n}\right) z_{\lambda}\left(\tau_{1}\right)+B_{n} b_{\lambda}\left(\tau_{1}\right)=-2 Q_{1} / n \pi \\
\left(A_{n}-a_{n}\right) z_{\lambda}^{\prime}\left(\tau_{1}\right)+B_{n} b_{\lambda}^{\prime}\left(\tau_{1}\right)=0 \\
\left(A_{n}-C_{n}\right) z_{\lambda}\left(\tau_{2}\right)+\left(B_{n}-D_{n}\right) \zeta_{\lambda}\left(\tau_{2}\right)=(-1)^{n} 2 Q_{2} / n \pi \\
\left(A_{n}-C_{n}\right) z_{\lambda}^{\prime}\left(\tau_{2}\right)+\left(B_{n}-D_{n}\right) \zeta_{\lambda}^{\prime}\left(\tau_{2}\right)=0
\end{gathered}
$$

Solving this system and making use of (1.7), we obtain the coefficients $a_{n}, A_{n}, \ldots, D_{n}$. This determines stream functions (1.5). The final solution of the problem is of the form

$$
\begin{gather*}
\psi_{1}(\tau, \theta)=\frac{2 Q}{\sigma \pi} \sum_{n=1}^{\infty} \frac{1}{\lambda} f_{\lambda}(\tau) \sin \lambda \theta, \quad \psi_{2}(\tau, \theta)=Q_{1} \frac{\sigma \pi-\theta}{\sigma \pi}+\frac{2 Q}{\sigma \pi} \sum_{n=1}^{\infty} \frac{1}{\lambda} g_{\lambda}(\tau) \sin \lambda \theta  \tag{1.9}\\
\psi_{3}(\tau, \theta)=Q_{1}-Q \frac{\theta}{\sigma \pi}+\frac{2 Q}{\sigma \pi} \sum_{n=1}^{\infty} \frac{1}{\lambda} x_{\lambda}(\tau) \sin \lambda \theta
\end{gather*}
$$

Here we have used the notation

$$
\begin{gather*}
f_{\lambda}(\tau)=\left[-\cos \lambda m+\varepsilon_{1} \frac{T_{\lambda}^{\prime}\left(\tau_{1}, \tau_{3}\right)}{w_{\lambda}\left(\tau_{1}\right)}+(-1)^{n} e_{2} \frac{T_{\lambda}^{\prime}\left(\tau_{1}, \tau_{3}\right)}{w_{\lambda}\left(\tau_{2}\right)}\right] \frac{z_{\lambda}(\tau)}{z_{\lambda}\left(\tau_{3}\right)} \\
g_{\lambda}(\tau)=\varepsilon_{1} \frac{z_{\lambda}^{\prime}\left(\tau_{1}\right)}{\tau_{\lambda}\left(\tau_{3}\right)} \frac{T_{\lambda}\left(\tau, \tau_{3}\right)}{w_{\lambda}\left(\tau_{1}\right)}+\left[-\cos \lambda m+(-1)^{n} e_{2} \frac{T_{\lambda}^{\prime}\left(\tau_{2}, \tau_{3}\right)}{w_{\lambda}\left(\tau_{2}\right)}\right] \frac{z_{\lambda}(\tau)}{z_{\lambda}\left(\tau_{3}\right)} \\
\chi_{\lambda}(\tau)=-\frac{z_{\lambda}(\tau)}{z_{\lambda}\left(\tau_{3}\right)} \cos \lambda m+\left[e_{1} \frac{z_{\lambda}^{\prime}\left(\tau_{1}\right)}{w_{\lambda}\left(\tau_{1}\right)}+(-1)^{n} e_{2} \frac{z_{\lambda}^{\prime}\left(\tau_{2}\right)}{w_{\lambda}\left(\tau_{2}\right)}\right] \frac{T_{\lambda}\left(\tau_{1} \tau_{3}\right)}{Z_{\lambda}\left(\tau_{3}\right)} \tag{1.10}
\end{gather*}
$$

in which $\left[{ }^{10}\right]$

$$
\begin{gather*}
T_{\lambda}\left(\tau_{1} \tau_{3}\right)=z_{\lambda}(\tau) \zeta_{\lambda}\left(\tau_{3}\right)-\zeta_{\lambda}(\tau) z_{\lambda}\left(\tau_{3}\right), \quad T_{\lambda}\left(\tau_{i}, \tau_{i}\right)=0  \tag{1,11}\\
T_{\lambda^{\prime}}\left(\tau_{i}, \tau_{3}\right)=\left[T_{\lambda}^{\prime}\left(\tau, \tau_{3}\right)\right]_{\tau=\tau_{i}}, \quad T_{\lambda}^{\prime}\left(\tau_{i}, \tau_{i}\right)=w_{\lambda}\left(\tau_{i}\right) \quad(i=1,2,3) \\
\varepsilon_{1}=\frac{Q_{1}}{Q}=\frac{h_{1} v_{1}\left(1-\tau_{\lambda}\right)^{\beta}}{\delta v_{3}\left(1-\tau_{3}\right)^{\beta}}, \quad \varepsilon_{2}=\frac{Q_{2}}{Q}=\frac{h_{9} v_{2}\left(1-\tau_{2}\right)^{\beta}}{\delta v_{3}\left(1-\tau_{3}\right)^{\beta}} \tag{1.12}
\end{gather*}
$$

We can readily verify from (1.10)-(1.12) that

$$
\begin{align*}
x_{\lambda}\left(\tau_{3}\right)= & -\cos \lambda m \\
x_{\lambda}^{\prime}\left(\tau_{3}\right)=\frac{\lambda_{1}}{\tau_{3}}\left[-x_{\lambda}\left(\tau_{3}\right) \cos \lambda m+\right. & \frac{h_{1}}{\delta}\left(\frac{\tau_{1}}{\tau_{3}}\right)^{1 / 3} \frac{z_{\lambda}\left(\tau_{1}\right)}{z_{\lambda}\left(\tau_{3}\right)} x_{\lambda}\left(\tau_{1}\right)+ \\
& \left.+(-1)^{n} \frac{h_{2}}{\delta}\left(\frac{\tau_{2}}{\tau_{3}}\right)^{1 / 2} \frac{z_{\lambda}\left(\tau_{2}\right)}{z_{\lambda}\left(\tau_{3}\right)} x_{\lambda}\left(\tau_{2}\right)\right] \tag{1.13}
\end{align*}
$$

The latter expression was obtained by differentiating (1.10), setting $\tau=\tau_{3}$, applying (1.7), and introducing the Chaplygin functions

$$
x_{\lambda}(\tau)=\frac{\tau z_{\lambda}^{\prime}(\tau)}{\lambda z_{\lambda}(\tau)}
$$

From solution (1.9) for $\sigma=1$ we can obtain Makeev's solution [ ${ }^{10}$ ] and other special cases mentioned in his paper.

When $h_{1}=h_{2}, v_{1}=v_{2}, \rho_{1}=\rho_{2}, Q_{1}=Q_{2}$ we obtain from (1.9) the solution for the symmetrical case (Den Gan Kho [11]).
2. Let us determine the compression coefficient and angle of deviation of the jet. Since we shall be using the function $\psi_{s}(\tau, \hat{\theta})$ only, we shall simply write $\psi(\tau, \theta)$. Along any jet surface we have

$$
\begin{equation*}
d y=2 \tau \frac{(1-\tau)^{-\beta}}{v} \frac{\partial \psi}{\partial \tau} \sin \theta d \theta, \quad d x=2 \tau \frac{(1-\tau)^{-\beta}}{\nu} \frac{\partial \psi}{\partial \tau} \cos \theta d \theta \tag{2.1}
\end{equation*}
$$

Substituting the stream function $\psi(\tau, \theta)$ into (2.1), integrating over $\theta$ from 0 to $\theta$, and setting $\tau=\tau_{3}$, we obtain the parametric equations of the jet contour $A M$

$$
\begin{gather*}
y=h_{1}+\frac{4 Q}{\sigma \pi} \frac{\tau_{g}\left(1-\tau_{3}\right)^{-9}}{v_{3}} \sum_{n=1}^{\infty} \frac{\chi_{\lambda}{ }^{\prime}\left(\tau_{3}\right)}{2 \lambda}\left[\frac{\sin (\lambda-1) \theta}{\lambda-1}-\frac{\sin (\lambda+1) \theta}{\lambda+1}\right]  \tag{2,2}\\
x=\frac{4 Q}{\sigma \pi} \frac{\tau_{3}\left(1-\tau_{s}\right)^{-9}}{v_{3}}\left\{\sum_{n=1}^{\infty} \frac{\chi_{\lambda}^{\prime}\left(\tau_{3}\right)}{\lambda^{2}-1}-\sum_{n=1}^{\infty} \frac{\chi_{\lambda}^{\prime}\left(\tau_{3}\right)}{2 \lambda}\left[\frac{\cos (\lambda-1) \theta}{\lambda-1}+\frac{\cos (\lambda+1) \theta}{\lambda+1}\right]\right\}
\end{gather*}
$$

In similar fashion we obtain the equations of the contour $F N$

$$
\begin{gather*}
y^{\prime}=-h_{3} \cos \sigma \pi+\frac{4 Q}{\sigma \pi} \frac{\tau_{3}\left(1-\tau_{s}\right)^{-\beta}}{v_{s}} \times \\
\times\left\{\sin \sigma \pi \sum_{n=1}^{\infty}(-1)^{n} \frac{\chi_{\lambda}^{\prime}\left(\tau_{3}\right)}{\lambda^{2}-1}+\sum_{n=1}^{\infty} \frac{\chi_{\lambda}^{\prime}\left(\tau_{s}\right)}{2 \lambda}\left[\frac{\sin (\lambda-1) \theta}{\lambda-1}-\frac{\sin (\lambda+1) \theta}{\lambda+1}\right]\right\} \\
x^{\prime}=h_{2} \sin \sigma \pi+\frac{4 Q}{\sigma \pi} \frac{\tau_{3}\left(1-\tau_{8}\right)^{-\beta}}{v_{3}} \times \tag{2.3}
\end{gather*}
$$

$\times\left\{\cos \Delta \pi \sum_{n=1}^{\infty}(-1)^{n} \frac{x_{\lambda}{ }^{\prime}\left(\tau_{s}\right)}{\lambda^{2}-1}-\sum_{n=1}^{\infty} \frac{x_{\lambda}{ }^{\prime}\left(\tau_{s}\right)}{2 \lambda}\left[\frac{\cos (\lambda-1) \theta}{\lambda-1}+\frac{\cos (\lambda+1) \theta}{\lambda+1}\right]\right\}$

Here $x^{\prime}, y^{\prime}$ are the coordinates of points on the contour $F N$.
In order to find the relationships among the parameters of the problem we make use of Zhukovskii's assumption[ ${ }^{12}$ ] that the points $M$ and $N$ lie on equipotential lines. Under this assumption we have

$$
\begin{equation*}
y_{M}-y_{N}^{\prime}=\delta \cos m, x_{N}^{\prime}-x_{M}=\delta \sin m \tag{2.4}
\end{equation*}
$$

Recalling (2.2) and (2.3), we transform (2.4) into

$$
\begin{gather*}
\delta \cos m=h_{1}+h_{2} \cos \sigma \pi-4 \delta \tau_{3} \frac{\sin \sigma \pi}{\sigma \pi} \sum_{n=1}^{\infty} \frac{(-1)^{n}}{\lambda^{2}-1} \chi_{\lambda}{ }^{\prime}\left(\tau_{3}\right)  \tag{2.5}\\
\delta \sin m=h_{2} \sin \sigma \pi+\frac{4 \delta \tau_{3}}{\sigma \pi}\left[\cos \sigma \pi \sum_{n=1}^{\infty} \frac{(-1)^{n}}{\lambda^{2}-1} \chi_{\lambda}{ }^{\prime}\left(\tau_{3}\right)-\sum_{n=1}^{\infty} \frac{\chi_{\lambda}{ }^{\prime}\left(\tau_{3}\right)}{\lambda^{2}-1}\right] \tag{2.6}
\end{gather*}
$$

To these equations we add continuity equation (1.1), which we rewrite as

$$
\delta v_{3}\left(1-\tau_{3}\right)^{\beta}=h_{1} v_{1}\left(1-\tau_{1}\right)^{\beta}+h_{2} v_{2}\left(1-\tau_{2}\right)^{\beta}
$$

From this we obtain

$$
\begin{equation*}
\delta=h_{1}\left(\frac{\tau_{1}}{\tau_{8}}\right)^{1 / 3}\left(\frac{1-\tau_{1}}{1-\tau_{3}}\right)^{\beta}+h_{2}\left(\frac{\tau_{2}}{\tau_{3}}\right)^{1 / 1 /}\left(\frac{1-\tau_{2}}{1-\tau_{3}}\right)^{\beta} \tag{2.7}
\end{equation*}
$$

Dividing (2.6) by (2.5) and recalling (1.13), (2.7), we obtain

$$
\begin{gather*}
\operatorname{tg} m=\left\{\Omega_{\lambda}\left(\tau_{1}, m\right)-\Pi_{\lambda}\left(\tau_{1}\right)+v\left[\sin \sigma \pi+\Omega_{\lambda}\left(\tau_{2}, m\right)+H_{\lambda}\left(\tau_{2}\right)\right]+\right. \\
\left.+\left[\Phi_{\lambda}\left(\tau_{1}, m\right)-H_{\lambda}\left(\tau_{1}\right)+v \Phi_{\lambda}\left(\tau_{2}, m\right)+v \Pi_{\lambda}\left(\tau_{2}\right)\right] \cos \sigma \pi\right\} \times \\
\times\left(1,+v \cos \sigma \pi-\left[\Phi_{\lambda}\left(\tau_{1}, m\right)-H_{\lambda}\left(\tau_{1}\right)+v \Phi_{\lambda}\left(\tau_{2}, m\right)+\right.\right. \\
\left.\left.v \Pi_{\lambda}\left(\tau_{2}\right)\right] \sin \cdot \sigma \pi\right\}^{-1} \tag{2.8}
\end{gather*}
$$

Here

$$
\begin{gather*}
H_{\lambda}(\tau)=\frac{4}{\sigma \pi}\left(\frac{\tau}{\tau_{3}}\right)^{1 / 2} \sum_{n=1}^{\infty}(-1)^{n-1} \frac{\lambda}{\lambda^{2}-1} \frac{i_{\lambda}(\tau)}{\Sigma_{\lambda}\left(\tau_{3}\right)} x_{\lambda}(\tau) \\
\Pi_{\lambda}(\tau)=\frac{4}{\sigma \pi}\left(\frac{\tau}{\tau_{3}}\right)^{1 / 2} \sum_{n=1}^{\infty} \frac{\lambda}{\lambda^{2}-1} \frac{z_{\lambda}(\tau)}{z_{\lambda}\left(\tau_{3}\right)} x_{\lambda}(\tau) \\
\Phi_{\lambda}(\tau, m)=\frac{4 \Delta\left(\tau, \tau_{3}\right)}{\sigma \pi} \sum_{n=1}^{\infty}(-1)^{n-1} \frac{\lambda}{\lambda^{3}-1} x_{\lambda}\left(\tau_{3}\right) \cos \lambda m  \tag{2.9}\\
\Omega_{\lambda}(\tau, m)=\frac{4 \Delta\left(\tau, \tau_{3}\right)}{\sigma \pi} \sum_{n=1}^{\infty} \frac{\lambda}{\lambda^{2}-1} x_{\lambda}\left(\tau_{3}\right) \cos \lambda m, \\
\nu=\frac{h_{3}}{h_{1}}, \quad \Delta\left(\tau, \tau_{3}\right)=\left(\frac{\tau}{\tau_{3}}\right)^{1 / 1}\left(\frac{1-\tau}{1-\tau_{3}}\right)^{\beta}
\end{gather*}
$$

From (2.5) with allowance for (1.13), (2.7), (2.9) we find that

$$
\begin{equation*}
v=\frac{1-\Delta\left(\tau_{1}, \tau_{3}\right) \cos m+\left[H_{\lambda}\left(\tau_{1}\right)-\Phi_{\lambda}\left(\tau_{1}, m\right)\right] \sin ब \pi}{\Delta\left(\tau_{2}, \tau_{3}\right) \cos m-\cos \sigma \pi+\left[\Pi_{\lambda}\left(\tau_{2}\right)+\Phi_{\lambda}\left(\tau_{2}, m\right)\right] \sin \sigma \pi} \tag{2,10}
\end{equation*}
$$

By the "compression coefficient" of the confluent asymmetric jet we mean the ratio of the smallest width 8 of this jet to the sum $h_{1}+\bar{h}_{3}$ We then find directly from Eq. (2.7) that

$$
\begin{equation*}
k=\frac{8}{h_{1}+h_{2}}=\frac{1}{1+v}\left(\frac{\tau_{1}}{\tau_{3}}\right)^{1 / 2}\left(\frac{1-\tau_{1}}{1-\tau_{3}}\right)^{\beta}+\frac{v}{1+v}\left(\frac{\tau_{2}}{\tau_{2}}\right)^{1 / 2}\left(\frac{1-\tau_{1}}{1-\tau_{2}}\right)^{\beta} \tag{2.11}
\end{equation*}
$$

Relations (2.8), (2.10), and (2.11) give us $\boldsymbol{m}, \boldsymbol{v}, k$ as functions of $\tau_{1}, \tau_{\mathbf{2}}, \tau_{\mathbf{3}}, \sigma \boldsymbol{\pi}$. Let us consider some special cases.

Case 1. Let us set $\sigma=1, \lambda=n$. We note that ( 2.9 ) yields the equations

$$
\begin{gather*}
\lim _{\sigma \rightarrow 1}\left[\Omega_{\lambda}(\tau, m)+\Phi_{\lambda}(\tau, m) \cos \sigma \pi\right]=\Omega_{m}(\tau, m) \\
\lim _{\sigma \rightarrow 1}\left[I I_{\lambda}(\tau)+H_{\lambda}(\tau) \cos \sigma \pi\right]=\Pi_{2 n}(\tau) \\
\lim _{\sigma \rightarrow 1}\left[H_{\lambda}(\tau)+\Pi_{\lambda}(\tau) \cos \sigma \pi\right]=-\Pi_{2 n}(\tau) \\
\lim _{\sigma \rightarrow 1} \Phi_{\lambda}(\tau, m) \sin \sigma \pi=2 \Delta\left(\tau, \tau_{s}\right) x_{1}\left(\tau_{3}\right) \cos m  \tag{2.12}\\
\\
\lim _{\sigma \rightarrow 1} H_{\lambda}(\tau) \sin \sigma \pi=2\left(\frac{\tau}{\tau_{z}}\right)^{1 / 1} \frac{s_{1}(\tau)}{\tau_{1}\left(\tau_{2}\right)} x_{1}(\tau)
\end{gather*}
$$

The function $z_{1}(\tau)$ is elementary [ ${ }^{7}$ ],

$$
z_{1}(\tau)=\frac{1-(1-\tau)^{\beta+1}}{(\beta+1) \tau^{1 / 2}}
$$

We therefore have

$$
\begin{align*}
x_{1}(\tau) & =-\frac{1}{2}+(\beta+1) \frac{\tau(1-\tau)^{\beta}}{1-(1-\tau)^{\beta+1}}  \tag{2.13}\\
\frac{z_{1}(\tau)}{z_{1}\left(\tau_{\tau}\right)} x_{1}(\tau) & =\frac{1}{2}\left(\frac{\tau_{2}}{\tau}\right)^{1 / 2} \frac{(1-\tau)^{\beta}[1+(2 \beta+1) \tau-1}{1-\left(1-\tau_{\varepsilon}\right)^{\beta+1}}
\end{align*}
$$

Recalling (2.12), (2.13), we transform (2.10), (2.8) into

$$
\begin{gather*}
\cos m=\frac{1+(2 \beta+1) \tau_{1}}{2(\beta+1)\left(\tau_{1} \tau_{3}\right)^{1 / 2}}\left[1-v \frac{1+(2 \beta+1) \tau_{2}}{1+(2 \beta+1) \tau_{1}}\left(\frac{1-\tau_{2}}{1-\tau_{1}}\right)^{\beta}-\right.  \tag{2,14}\\
\left.-\frac{(1-v)\left(1-\tau_{3}\right.}{1+(2 \beta+1) \tau_{1}}\left(\frac{1-\tau_{1}}{1-\tau_{1}}\right)^{\beta}\right]\left[1+v\left(\frac{\tau_{2}}{\tau_{2}}\right)^{1 / 2}\left(\frac{1-\tau_{2}}{1-\tau_{2}}\right)^{\beta}\right]^{-1} \\
v=\frac{\Omega_{2 n}\left(\tau_{1}, m\right)-\Pi_{2 n}\left(\tau_{1}\right)-\Delta\left(\tau_{1}, \tau_{g}\right) \sin m}{\Delta\left(\tau_{2}, \tau_{s}\right) \sin m+\Pi_{2 n}\left(\tau_{2}\right)-\Omega_{2 n}\left(\tau_{2}, m\right)} \tag{2.15}
\end{gather*}
$$

respectively.
In this special case Eq. (2.14) follows directly from the familiar Euler theorem.
Case 2. We set $\sigma=1 / 2, \lambda=2 n$. Here (2.8), (2.10) become

$$
\begin{gather*}
\operatorname{tg} m=\frac{\Omega_{2 n}\left(\tau_{1}, m\right)-\Pi_{2 n}\left(\tau_{1}\right)+v\left(1+\Omega_{2 n}\left(\tau_{2}, m\right)+H_{2 n}\left(\tau_{2}\right)\right]}{1+H_{2 n}\left(\tau_{1}\right)-\Phi_{2 n}\left(\tau_{1}, m\right)-v\left[\Pi_{2 n}\left(\tau_{2}\right)+\Phi_{2 n}\left(\tau_{2}, m\right)\right]}  \tag{2.16}\\
v=\frac{1-\Delta\left(\tau_{1}, \tau_{8}\right) \cos m+H_{2 n}\left(\tau_{1}\right)-\Phi_{2 n}\left(\tau_{1}, m\right)}{\Delta\left(\tau_{2}, \tau_{2}\right) \cos m+\Pi_{2 n}\left(\tau_{2}\right)+\Phi_{2 n}\left(\tau_{2}, m\right)} \tag{2.17}
\end{gather*}
$$

3. In the case of an incompressible fluid

$$
\lim _{v_{\max } \rightarrow \infty} \frac{z_{\lambda}(\tau)}{z_{\lambda}\left(\tau_{3}\right)}=\left(\frac{v}{v_{3}}\right)^{\lambda} ; \quad \lim _{\operatorname{limax}_{\max }} x_{\lambda}(\tau)=\frac{1}{2}, \lim _{v_{\max } \rightarrow \infty} \Delta\left(\tau, \tau_{3}\right)=\frac{v}{v_{3}}
$$

and expressions (2.8), (2.10), (2.11) become
tg $m=\left\{\Omega_{\lambda}{ }^{0}\left(v_{1}, m\right)-\Pi_{\lambda}{ }^{0}\left(v_{1}\right)+v\left[\sin \sigma \pi+\Omega_{\lambda}{ }^{\circ}\left(v_{2}, \quad m\right)+H_{\lambda}{ }^{0}\left(v_{2}\right)\right]+\right.$


Table

| $t$ | $v_{z} / v_{1}$ | $\checkmark$ | m | k |  | $v_{2} v_{1}$ |  | m | $k$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $q=0.20$ |  |  |  |  | $q=0.50$ |  |  |  |  |
| 0.55 | 2.750 | 0.106 | $32^{\circ} 04^{\prime}$ | 0.517 | 0.40 | 0.800 | 1.225 | $54^{\circ} 37^{\prime}$ | 0.469 |
| 0.60 | 3.000 | 1.652 | 6105 | 0.351 | 0.45 | 0.900 | 0.237 | 2617 | 0.460 |
| 0.60 | 3.000 | 2.471 | 6457 | 0.315 | 0.45 | 0.900 | 3.388 | 6012 | 0.489 |
| 0.65 | 3.250 | 0.812 | 5314 | 0.448 | 0.50 | 1.000 | 0.192 | 2522 | 0.500 |
| 0.70 | 3.500 | 0.589 | 5000 | 0.515 | 0.50 | 1.000 | 5.217 | 6346 | 0.500 |
| 0.70 | 3.500 | 1.947 | 6203 | 0.370 | 0.55 | 1.100 | 0.159 | 2442 | 0.543 |
| 0.75 0.80 | 3.750 4.000 | 1.055 0.359 | 5655 4555 | 0.468 0.642 | 0.60 | 1.200 | 0.133 | 2412 | 0.588 |
| 0.80 | 4.000 | 0.716 | 5342 | 0.550 | 0.60 | 1.200 | 1.252 6.159 | 4356 | 0.544 |
| 0.85 | 4.250 | 0.283 | 4410 | 0.707 | ${ }_{0} 0.65$ | 1.300 | 0.113 | 6311 2347 | 0.514 0.635 |
| 0.85 | 4.250 | 0.512 | 5058 | 0.630 | 0.65 | 1.300 | 0.864 | 3947 | 0.580 |
| 0.90 | 4.500 | 0.219 | 4216 | 0.774 | 0.70 | 1.400 | 0.096 | 2326 | 0.682 |
| 0.90 | 4.500 | 0.366 | 4811 | 0.712 | 0.70 | 1.400 | 0.650 | 3707 | 0.621 |
| $q=0.30$ |  |  |  |  | 0.75 | 1.500 | 0.082 | 2308 | 0.731 |
| U. 55 | 1.833 | 0.760 | $46^{\circ} 34{ }^{\prime}$ | 0.442 | 0.75 | 1.500 | 0.505 0.069 | 3501 <br> 2250 <br> 23 | 0.666 0.781 |
| 0.55 | 1.833 | 3.120 | 6416 | 0.361 | 0.80 | 1.600 | 0.069 | 22519 | 0.781 0.715 |
| 0.60 | 2.000 | 0.538 | 4235 | 0.495 | 0.85 | 1.700 | 0.058 | 2232 | 0.831 |
| 0.65 | 2.167 | 0.418 | 4015 | 0.335 | 0.85 | 1.700 | 0.310 | 3141 | 0.767 |
| 0.65 | 2.167 | 2.163 | 5851 | 0.5411 | 0.90 0.90 | 1.800 | 0.047 | 2212 | 0.882 |
| 0.65 | 2.167 | 4.456 | 6511 | 0.364 | 0.90 | 1.800 | 0.238 | 3002 | 0.823 |
| 0.70 | 2.333 | 0.337 | 3833 | 0.599 | $q=0.60$ |  |  |  |  |
| 0.70 | 2.333 | 1.077 | 5136 | 0.493 |  |  |  |  |  |
| 0.75 | 2.500 | 0.275 | 3711 | 0.653 | 0.20 0.20 |  | 0.405 0.606 |  | 0.315 0.351 |
| 0.75 | 2.500 | 0.745 | 4804 | 0.558 | 0.20 0.25 | 0.333 0.417 | 0.606 0.191 | 2855 2100 | 0.351 0.306 |
| 0.80 0.80 | 2.667 | 0.225 | 3559 | 0.708 | 0.25 | 0.417 | 1.265 | 4011 | 0.446 |
| 0.80 0.85 | 2.667 2.833 | 0.549 0.183 | 4522 3448 | 0.623 0.765 | 0.30 | 0.500 | 0.133 | 1957 | 0.335 |
| 0.85 | 2.833 | 0.411 | 4259 | 0.690 | 0.30 | 0.500 | 1.860 | 4725 | 0.495 |
| 0.90 | 3.000 | 0.145 | 3332 | 0.824 | 0.35 | 0.583 | 0.102 | 1924 | 0.373 |
| 0.90 | 3.000 | 0.304 | 4033 | 0.760 | 0.35 0.40 | 0.583 | 2.588 | 5315 1903 | ${ }_{0}^{0.530}$ |
| $q=0.40$ |  |  |  |  | 0.40 | 0.667 | 3.580 | 5808 | 0.556 |
| 0.45 | 1.125 | 0.646 | $39^{\circ} 28^{\prime}$ | 0.430 | 0.45 | 0.750 | 0.067 | 1849 | 0.459 |
| 0.45 | 1.125 | 1.804 | 5445 | 0.418 | 0.45 | 0.750 | 5.057 | 6215 | 0.575 |
| 0.50 | 1.250 | 0.445 | 3523 | 0.469 | 0.50 | 0.833 | 0.056 | 1831 | 0.505 |
| 0.50 | 1.250 | 3.260 | 6217 | 0.423 | 0.50 | 0.833 | 7.500 | 6548 | 0.588 |
| 0.55 | 1.375 | 0.345 | 3317 | 0.512 | 0.55 | 0.917 | 0.048 | 1830 | 0.552 |
| 0.55 | 1.375 | 5.807 | 6712 | 0.422 | 0.55 | 0.917 | 1.424 | 4050 | 0.579 |
| 0.60 | 1.500 | 0.279 | 3151 | 0.556 | 0.55 | 0.917 | 4.770 | 5754 | 0.591 |
| 0.65 | 1.625 | 0.230 | 3050 | 0.603 | 0.60 | 1.000 | 0.041 | 1823 | 0.600 |
| 0.65 | 1.625 | 1.141 | 4725 | 0.517 | 0.60 | 1.000 | 0.970 | 3614 | 0.60 ) |
| 0.70 | 1.750 | 0.192 | 2959 | 0.652 | 0.60 | 1.000 | 9.687 | 6448 | 0.600 |
| 0.70 | 1.750 | 0.792 | 4337 | 0.567 | 0.65 | 1.083 | 0.035 | 1817 | 0.648 |
| 0.75 | 1.875 | 0.161 | 2916 | 0.701 | 0.65 | 1.083 | 0.734 | 3331 | 0.621 |
| 0.75 | 1.875 | 0.592 | 4058 | 0.620 | 0.70 | 1.167 | 0.030 | 1812 | $0.69{ }^{\prime}$ |
| 0.80 | 2.000 | 0.134 | 2836 | 0.753 | 0.70 | 1.167 | 0.575 | 3131 | 0.664 |
| 0.80 | 2.000 | 0.454 | 3848 | 0.675 | 0.75 | 1.250 | 0.028 | 1807 | 0.74 |
| 0.85 | 2.125 | 0.111 | 2756 | 0.805 | 0.75 | 1.250 | 0.458 | 2953 | 0.703 |
| 0.85 | 2.125 | 0.349 | 3649 | 0.734 | 0.80 | 1.333 | 0.022 | 4802 | 0.796 |
| 0.90 | 2.250 | 0.090 | 2713 | 0.859 | 0.80 | 1.333 | 0.366 | 2826 | 0.74 |
|  |  |  |  |  | 0.85 | 1.417 | 0.018 | 1757 | 0.846 |
|  |  |  |  |  | 0.85 | 1.417 | 0.291 | 2704 | 0.794 |
|  |  |  |  |  | 0.90 | 1.500 | 0.015 | 1752 | 0.896 |
| 0.35 | 0.700 | 0.443 | $30^{\circ} 35^{\circ}$ | 0.396 | 0.90 | 1.500 | 0.220 | 2541 | 0.845 |
| 0.35 | 0.700 | 1.400 | 4649 | 0.438 |  |  |  |  |  |
| 0.40 | 0.800 | 0.307 | 2743 | 0.424 |  |  |  |  |  |

Table (continued)

|  | $v_{z} / v_{\text {k }}$ |  | m | * | $t$ | $v_{2} / v_{1}$ | * | m | k |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $q=0.70 \quad q=0.80$ |  |  |  |  |  |  |  |  |  |
| 0.15 | 0.214 | 1.200 | $32^{\circ} 56^{\prime}$ | 0.450 | 0.50 | 0.625 | 7.342 | 5638 | 0.764 |
| 0.20 | 0.286 | 1.698 | 4000 | 0.515 | 0.55 | 0.688 | 1.003 | 2523 | 0.675 |
| 0.25 | 0.357 | 2.268 | 4608 | 0.562 | 0.60 | 0.750 | 0.804 | 2327 | 0.689 |
| 0.30 | 0.428 | 2.971 | 5127 | 0.599 | 0.65 | 0.812 | 0.655 | 2457 | 0.709 |
| 0.35 | 0.500 | 3.896 | 5602 | 0.628 | 0.70 | 0.875 | 0.538 | 2041 | 0.735 |
| 0.40 | 0.571 | 5.194 | 6004 | 0.652 | 0.75 | 0.938 | 0.444 | 1934 | 0.765 |
| 0.45 | 0.643 | 7.156 | 6329 | 0.669 | 0.80 | 1.000 | 0.364 | 1832 | 0.800 |
| 0.50 | 0.714 | 1.659 | 3742 | 0.625 | 0.85 | 1.062 | 0.296 | 1731 16 | 0.839 |
| 0.50 | 0.714 | 4.227 | 5241 | 0.662 | 0.90 | 1.125 | 0.235 | 1628 | 0.881 |
| 0.55 | 0.786 | 1.118 | 3235 | 0.629 | $q=0.90$ |  |  |  |  |
| 0.55 | 0.786 | 7.755 | 6032 | 0.683 |  |  |  |  |  |
| 0.60 | 0.857 | 0.851 | 2948 | 0.646 0.670 | 0.15 | 0.167 0.222 | 3.724 4.571 | 4150 474 48 | 0.741 0.774 |
| 0.65 0.70 | 0.928 1.000 | 0.673 0.542 | 2749 2614 | 0.670 0.700 | 0.20 | 0.222 0.278 | 4.571 5.593 | 4744 52 50 | 0.774 |
| 0.70 0.75 | 1.000 1.071 | 0.542 | ${ }_{24}^{26} 54$ | 0.735 | 0.30 | 0.333 | 6.899 | 5628 | 0.824 |
| 0.80 | 1.143 | 0.356 | 2341 | 0.774 | 0.35 | 0.389 | 8.660 | 5950 | 0.843 |
| 0.85 | 1.214 | 0.286 | 2231 | 0.817 | 0.40 | 0.444 | 1.965 | 2456 | 0.732 |
| 0.90 | 1.286 | 0.225 | 2118 | 0.863 | 0.40 | 0.444 | 5.781 | 4704 | 0.826 |
| $q=0.80$ |  |  |  |  | 0.45 | 0.500 | 1.474 | 2109 | 0.718 |
|  |  |  |  |  | 0.45 | 0.500 | 8.469 | 5402 | 0.852 |
| 0.15 | 0.186 | 2.171 | $37^{\circ} 47^{\prime}$ | 0.595 | 0.50 | 0.556 | 1.176 | 1852 | 0.716 |
| 0.20 | 0.250 | 2.789 | 4405 | 0.642 | 0.55 | 0.611 | 0.962 | 1712 | 0.722 |
| 0.25 | 0.312 | 3.522 | 4927 | 0.678 | 0.60 | 0.667 | 0.798 | 1554 | 0.733 |
| 0.30 | 0.375 | 4.447 | 5401 | 0.708 | 0.65 | 0.722 | 0.667 | 1448 | 0.750 |
| 0.35 | 0.438 | 5.684 | 5758 | 0.733 | 0.70 | 0.778 | 0.558 | 1350 | 0.772 |
| 0.40 | 0.500 | 7.434 | 6124 | 0.753 | 0.75 | 0.834 | 0.467 | 1258 | 0.798 |
| 0.45 | 0.562 | 1.886 | 3315 | 0.679 | 0.80 | 0.889 | 0.389 | 1208 | 0.828 |
| 0.45 | 0.562 | 4.380 | 4827 | 0.735 | 0.85 | 0.945 | 0.320 | 11 11 10 | 0.862 0.900 |
| 0.50 | 0.625 | 1.300 | $28^{\circ} 08^{\prime}$ | 0.670 | 0.90 | 1.000 | 0.257 | 1027 | 0 |

Formulas (3.3) were used to carry ont detailed numerical computations whose results are given in the Table.

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Translated by A. Y.

# SELF-SIMILAR MOIIONS OF A RADIATION-HEATED GAS BEHIND THE ABSORPTION-INITIATING SHOCK WAVE FRONT 

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When acted on by sufficiently powerful light beams, gases which transmit radiation under ordinary conditions can experience breakdown. A survey of experimental data and theoretical information on this phenomenon will be found in [ ${ }^{1}$ ], one of whose aspects is the shifting of the absorption zone to meet the oncoming light beam.

The present paper concerns the motion of the gas and heating behind the absorption wave propagating solely as a result of one of the mechanisms noted in [1] (the hydrodynamic mechanism). The mechanism consists essentially in the following: a shock wave begins to propagate from the breakdown zone, which is characterized by the intensive release of energy and a considerable increase in pressure. Ionization occurs at the shock wave front, and this makes possible the absorption of radiation as a result of the braking mechanism.

The heating of the gas which results in excitation of the atoms and ions also produces absorption (because of the photoelectric effect from highly excited states). If the gas ahead of the front is cold and nonionized, then it usually transmits radiation in the optical range. Thus, the shock wave front marks the boundary at which radiation absorption begins (i.e. it initiates absorption and energy release due to absorption). There are, of course, other factors which can produce such shock waves (electrical discharges, vaporization of the surface of a solid body under one type of radiation or another, etc. ).

Absorption of radiation at small distances from the shock wave front produces a detonation wave [ ${ }^{1}$ ].

If the radiation flux incident on the shock wave front varies, then the detonation wave propagates with a variable velocity. It is of interest to consider gas motions behind the fronts of such shock waves. With a power law of variation of the radiation flux with time, $q \sim t^{\alpha}$, the velocity of the detonation wave also varies according to a power law, and the problem is self-similar.
It is also interesting to consider gas motion in cases where the radiation is absorbed at distances comparable with characteristic dimension of the problem, and even at distances such that the radiation passes almost freely through the heated gas behind the shock wave front (through optically thin gas layers).

1. The radiation absorption coefficient $\mathcal{x}$ due to free-free electron transitions in the ionic field depends on the temperature and density in the complete-ionization zone in the following way:

$$
x \sim \varepsilon^{-3} T^{-1 / 2} \rho \sim e^{-2} p^{-1:} 2 \rho^{6 / 2}
$$

Here $\varepsilon$ is the quantum energy, $T$ is the temperature, $\boldsymbol{p}$ is the pressure, and $\rho$ is the density.

In the multiple-ionization zone where absorption also occurs by way of the photoelectric effect from highly excited atomic and ionic states the function $\boldsymbol{x}(T, \rho)$ can also be approximated by means of a power function,

$$
\begin{equation*}
x=k_{q} \rho^{-a} p^{b}=k_{q} v^{a} p^{b} \tag{1.1}
\end{equation*}
$$

